Solving Global Optimization Problems With Constraints Via Branch and Bound Method Ch. Daili¹

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Abstract

The purpose of this paper is to present a new approach for solving a global optimization problem. It is the Branch and bound method applied to solve a DC programming problem with a separable concave part, in which we use two techniques of subdivision the first is called the largest distance bisection, denoted by (LDB) and the other is the w-subdivision. To calculate the lower bounds, we propose to solve the subproblems obtained by replacing the concave term in the objective function by a linear term. An algorithm is developed followed by a theorem of convergence and applications

Consider the following DC optimization problem :

$$\begin{cases} \min f(x) \\ Ax \le b, \\ l \le x \le u. \end{cases}$$
 (DCP)

where

$$\begin{split} f(x) &= g(x) + \varphi(x) \\ g \text{ is a convex function and } \varphi(x) &= \sum_{i=1}^{n} \varphi_i(x_i), \\ \text{The functions } \varphi_i(x_i), \, i = 1, ..., n, \text{ are concave functions.} \\ \text{The feasible domain is the intersection of the polytope} \end{split}$$

$$S = \left\{ x \in \mathbb{R}^n \ / \ Ax \le b \right\},\$$

Where

 $A \subset \mathbb{R}^{m \times n}, b \in \mathbb{R}^m$ and the rectangle defined by

$$D = \left\{ x \in \mathbb{R}^n \ / \ l \le x \le u \right\}.$$

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